

## Discrete Time Control Systems 2nd Ogata

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Ogata K. Discrete-Time Control Systems 2nd ed. (PH, 1995) (0133286428)

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The time optimal control problem in unforced discrete systems is studied in this thesis. Comparison is made between the discrete and the continuous control systems by means of miniml:t."Yl time isochrones. Concerning optimal time, it is shm .. n that using discrete control system t..rill take at most one

[On time-optimal second order discrete control systems](#)

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A comprehensive treatment of the analysis and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The book features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

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Discrete control systems, as considered here, refer to the control theory of discrete-time Lagrangian or Hamiltonian systems. Thesediscrete-time models are based on a discrete variational principle , andare part of the broader field of geometric integration .

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Such a discrete-time control system consists of four major parts: 1 The Plant which is a continuous-time dynamic system. 2 The Analog-to-Digital Converter (ADC). 3 The Controller ( $\mu P$ ), a microprocessor with a "real-time" OS. 4 The Digital-to-Analog Converter (DAC). 3 + - r(t) e(t) ADC  $\mu P$  DAC u(t) Plant ? ? y(t) 4

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Notes for Discrete-Time Control Systems (ECE-520) Fall 2010 by R. Throne The major sources for these notes are † Modern Control Systems, by Brogan, Prentice-Hall, 1991. † Discrete-Time Control Systems, by Ogata. Prentice-Hall, 1995. † Computer Controlled Systems, by "Astr"om and Wittenmark. Prentice-Hall, 1997.

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First, digital computers are, by design, discrete-time devices, so discrete- time signals and systems includes digital computers. Second, almost all the important ideas in discrete-time systems apply equally to continuous- time systems. Alas, even discrete-time systems are too diverse for one method of analy sis.

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Discrete-time control systems 2nd ed. This edition published in 1995 by Prentice-Hall International in London.

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The time interval between two discrete instants is taken to be sufficiently short that the data for the time between them can be approximated by simple interpolation. Discrete-time control systems differ from continuous-time control systems in that signals for a discrete-time control system are in sampled-data form or in digital form.

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(available) at all times. A typical continuous time control system is shown in Figure below. (Closed loop continuous-time control system) Discrete time Control System: Discrete time control systems are control systems in which one or more variables can change only at discrete instants of time. These instants, which may be denoted by  $kT$ ( $k=0,1,2,\dots$ )

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